# THEORETICAL STUDY OF STRESS TRANSFER IN PLATELET REINFORCED COMPOSITES 

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#### Abstract

An analytical approach was developed for rectangular platelet reinforced composites which could be used for a 3D elastic stress field distribution subjected to an applied axial load. The ends of the platelet could be bonded to the matrix. Exact displacement solutions were derived for the matrix/platelet fromtheory of elasticity. These displacement solutions were then superposed for achieving analytical expressions for the matrix/platelet 3D stress field components over the entire composite system including the platelet end region, using the adding imaginary fiber technique. The platelet/matrix components could exactly satisfy the equilibrium and compatibility conditions and satisfy the equilibrium requirements and the overall boundary conditions. The obtained analytical results were then validated by FEM and Shear-lag modeling, and some of discrepancies among the shear-lag models were resolved. Good agreements were observed between the analytical and numerical predictions.


Key words: analytical modeling, platelet reinforced composites, stress transfer

## 1. Introduction

Over the past few decades, a variety of numerical and analytical models has been developed to investigate different stress transfer problems in composites. These models mainly include 1D models, which are typically based on the shear-lag theory (Agarwal, 1974; Agarwal and Broutman, 1980; Chang and Tarn, 2011; Cox, 1952; Glavinchevski and Piggott, 1973; Haque and Ramasetty, 2005; Hsueh, 1994, 2000; Hsueh et al., 1999; Jiang and Peters, 2008; Jiang et al., 1998; Kim, 1998, 2007, 2008; Kim and Kwac, 2009; Kim and Noh, 2004; Kotha et al., 2000; Lusis et al., 1973; Narin, 1997, 2004; Narin and Mendels, 2001; Padawer and Beecher, 1970; Piggott, 1980; Salekin et al., 1992; Taya and Arsenault,1989; Tyson and Davies, 1965; Wu et al., 1997), 3D analytical models based on axisymmetric analyses (Abedian et al., 2007; Jiang et al., 1998, 2004; Wu et al., 1997), the Eshelby models based on Eshelby's equivalent inclusion method (Arsenault and Taya, 1987; Eshelby, 1957; Tanaka et al., 1973; Lee, 2008; Withers et al., 1989) and numerical models (Cannilloa et al., 2003; Lusti et al., 2002; Narin, 2007). Due to the complexity of elasticity field equations, analytical closed-form solutions to fully three-dimensional problems are very difficult to be obtained. Accordingly, many solutions have been developed for reduced problems that are typically composed of axisymmetry or one-dimensionality based on the shear-lag theory for simplifying a particular aspect of the formulation and solution. In mathematical terms, the shear-lag model is the simplest of all models, which is widely used for the stress transfer analysis in unidirectional composites. This model is based on a simple differential equation which relates the fibre axial stress to the interfacial shear stress. It is not applicable at higher volume fractions due to the significant interactions of fibres. Also, the model cannot predict changes of axial stress and strain distributions in the radial direction. As a result, due to these limitations, the shear-lag model cannot provide reliable predictions for the
composite properties, and thus, its application for short fibre composites has been limited over time. Most interfacial problems need the detailed distribution of stresses at the interface like the interface friction slip behavior in composites; however, the one-dimensional shear-lag model cannot provide this stress state. Three-dimensional analytical models have been developed based on quite different approaches and aim mostly at the interfacial problems. It has been noted that most of the three-dimensional analytical models usually satisfy the equilibrium states and most of the boundary and interfacial conditions. This is because the solutions are generally based on the stress equilibrium equations; but the compatibility conditions are only partly or approximately satisfied because of different degrees of applied approximations and simplifications. Therefore, since the excessive complicated mathematical derivations are involved, very limited efforts could be observed for the exact solution of such problems in the literature. One of the most precise and relatively simple three-dimensional analytical solutions was done by Jiang et al. (2004). In this model, two sets of exact displacement solutions for the matrix, i.e. the far-field solution and the transient solution, were derived. Afterwards, the theory of elasticity and superposition of the simplified analytical expressions were used to find all the stress components in the matrix and fibre. It is worth mentioning that the fibre end region could be also included using the imaginary fibre technique. Jiang's analytical model was modified and developed by Abedian et al. (2007). The latter was greatly improved and could predict capability of the composite behavior. In brief, for Jiang's and Abedian's models, the following assumptions were made: a perfect bond existed at the fibre-matrix interface and both fibre and matrix were isotropic.

Most authors have made emphasis on platelets as reinforcement instead of fibers because of their two-dimensional stiffening effects (Chou and Green, 1993; Piggott, 1980; Salekin et al., 1992) and cost factor. The two-dimensional stress transfer model of platelet reinforced composites was presented by Tyson and Davis (1965), which was derived following the same analysis as applied in the classical shear-lag model by Cox (1952). Later, Hsueh (1994, 1999, 2000) proposed a more rigorous two-dimensional stress transfer model for platelet reinforcement while assuming that the shear stress in the matrix decreased linearly from the interface between the platelet and matrix to the edges. Also, the effects of matrix bonding at the ends, Young's modulus, and the aspect ratio of the platelet were investigated on stress transfer. A simple second order model and a more complicated fourth order model were developed for simulating stress transfer in overlapped platelets by Kotha et al. (2000). Some other models based on shear-lag theory were presented by Narin (1999, 2001, 2004).

The present study tried to derive such an analytical 3D modeling of platelet reinforced composites which were presented according to Jiang's and Abedian's methods and boundary conditions. While considering the typical complexity of stress field distribution in platelet reinforced composites, the analysis aimed at a platelet reinforced composite subjected to an applied axial load. Two sets of matrix/platelet displacement solutions, the far-field solution and the transient solution were precisely derived based on the theory of elasticity and were superposed to achieve simplified analytical expressions for the matrix/platelet stress field components and the platelet axial stress field components in the entire composite system, which included the platelet end region, using the technique of adding the imaginary fibre. The finite element numerical calculations were then conducted to examine the validity of this analytical model. At last, some concluding remarks were presented on the present analytical model. Both bonded and debonded platelet end cases were introduced in this research.

## 2. Analyses

### 2.1. Composite model

In the current study, a rectangular unit cell (as shown in Fig. 1) was used for modeling platelet reinforced composites. The platelet with the width of $2 a$ and length of $2 l$ was embedded in the
center of a matrix with the width of $2 b$ and length of $2 l^{\prime}$. The area fraction and aspect ratio of the platelet were defined as follows $f=a / b$ and $s=l / a$, respectively. The axial stress $\left(\sigma_{0}\right)$ was considered to be uniformly applied to the end faces of the unit cell. A Cartesian coordinate system $(x, y)$ was also applied with its origin located in the centre of the unit cell, as given in Fig. 1. For simplicity, a perfect bond was assumed at the platelet/matrix interface and isotropic constituents for the composite. Due to the symmetric geometry in the x-y plane and boundary conditions, only one quarter of the unit cell was considered in the analysis. In this work, the solutions were performed in two separate areas: in the platelet region $(0 \leqslant y \leqslant l)$ and the platelet end region $\left(l \leqslant y \leqslant l^{\prime}\right)$. They were undertaken using the imaginary fibre technique (Abedian et al., 2007; Jiang et al., 2004), which assumed that the platelet end region was composed of an imaginary platelet surrounded with a rectangular matrix while the properties of the imaginary platelet were considered the same as those of the matrix.


Fig. 1. Schematic illustrations of the unit cell

### 2.2. General solutions of matrix and platelet displacements

The equilibrium equations for plane stresses (Timoshenko and Goodier, 1951) are as follows

$$
\begin{equation*}
\frac{\partial \sigma_{x}}{\partial x}+\frac{\partial \tau_{x y}}{\partial y}=0 \quad \frac{\partial \sigma_{y}}{\partial y}+\frac{\partial \tau_{x y}}{\partial x}=0 \tag{2.1}
\end{equation*}
$$

which lead to the equations

$$
\begin{equation*}
\frac{2}{1+\nu} \frac{\partial^{2} u}{\partial x^{2}}+\frac{1-\nu}{1+\nu} \frac{\partial^{2} u}{\partial y^{2}}+\frac{\partial^{2} w}{\partial x \partial y}=0 \quad \frac{1-\nu}{1+\nu} \frac{\partial^{2} w}{\partial x^{2}}+\frac{2}{1+\nu} \frac{\partial^{2} w}{\partial y^{2}}+\frac{\partial^{2} u}{\partial x \partial y}=0 \tag{2.2}
\end{equation*}
$$

where $u$ is the displacement in the $x$-direction, and $w$ is the displacement in the $y$-direction, $E$ s Young's modulus and $\nu$ is Poisson's ratio. By simple algebraic manipulation of the operators in Eqs. (2.1) and (2.2), the governing equations of $w$ and $u$ can be derived. The equation with respect to $u$ could be found in the following manner

$$
\begin{equation*}
\frac{\partial^{4} u}{\partial x^{4}}+2 \frac{\partial^{4} u}{\partial x^{2} \partial y^{2}}+\frac{\partial^{4} u}{\partial y^{4}}=0 \tag{2.3}
\end{equation*}
$$

The method of separation variables verifies the last equation and results in different answers. For the case of this reserach, the Laplace equation could be obtained according to the conditions (see Appendix A). Thus, the following general solution can be found for the $x$-direction displacement

$$
\begin{equation*}
u^{m(T)}(x, y)=\left(A_{1} \sin n x+A_{2} \cos n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \tag{2.4}
\end{equation*}
$$

where $A_{i}(i=1-4)$ is an integral constant and $n$ is a constant related to the eigenvalue. By substituting Eq. (2.4) into Eq. (2.1) or Eq. (2.2), the general solution for the $y$-direction displacement $(w)$ can be derived as follows

$$
\begin{equation*}
w^{m(T)}(x, y)=\left(-A_{1} \cos n x+A_{2} \sin n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right) \tag{2.5}
\end{equation*}
$$

Another set of the displacement general solutions for zero-eigenvalue were derived as demonstrated below (see Appendix A)

$$
\begin{equation*}
u^{m(0)}(x, y)=B_{1}+B_{2} x \quad w^{m(0)}(x, y)=B_{3}+B_{4} y \tag{2.6}
\end{equation*}
$$

where $B_{j}(j=1, \ldots, 4)$ is the integral constant. The above displacement solutions could be superimposed to write the total value of displacement components in the matrix as follows

$$
\begin{equation*}
u^{m}=u^{m(0)}+u^{m(T)} \quad w^{m}=w^{m(0)}+w^{m(T)} \tag{2.7}
\end{equation*}
$$

The general solutions for the $x$ - and $y$-directions displacements in the platelet could be found in Eqs. (2.8)-(2.10). It should be noted that, due to the continuity condition, $A_{3}$ and $A_{4}$ were considered the same as those for the matrix expressions. But new boundary conditions were required for successful application in these equations, as presented in the next section. The details of derivation of the coefficients by the proposed boundary conditions will be also given in this investigation

$$
\begin{align*}
& u^{p(T)}(x, y)=\left(A_{5} \sin n x+A_{6} \cos n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
& w^{p(T)}(x, y)=\left(-A_{5} \cos n x+A_{6} \sin n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right) \tag{2.8}
\end{align*}
$$

and

$$
\begin{equation*}
u^{p(0)}(x, y)=B_{5}+B_{6} x \quad w^{p(0)}(x, y)=B_{7}+B_{8} y \tag{2.9}
\end{equation*}
$$

and

$$
\begin{equation*}
u^{p}=u^{p(0)}+u^{p(T)} \quad w^{p}=w^{p(0)}+w^{p(T)} \tag{2.10}
\end{equation*}
$$

Thus, the general solutions for the stress and strain components which correspond to the above two sets of displacement solutions were obtained using Hook's law (see Appendix B). Therefore, the stress field described by displacement Eqs. (2.6) and (2.9) was identical to the one in a composite with infinitely long platelets which were subjected to a far-field load corresponding to the uniform portion of the total stress. However, the stress field described by Eqs. (2.4), (2.5), and (2.8) corresponded to the non-uniform portion of the total stress field since all the components of the stress field depended on both $x$ - and $y$-directions.

## 3. Solution for platelet

### 3.1. Far-field solution

The surface conditions for the far-field solution in the platelet region for the platelet bonded end case could be presented by

$$
\begin{equation*}
\tau_{x y}^{m(0)}(b, y)=0 \quad w^{m(0)}(x, 0)=0 \quad u^{p(0)}(0, y)=0 \tag{3.1}
\end{equation*}
$$

The above conditions and $\varepsilon_{y y}^{m(0)}=\varepsilon_{0}$ can be used for deriving the following constants

$$
\begin{equation*}
B_{3}=B_{5}=0 \quad B_{4}=\varepsilon_{0} \tag{3.2}
\end{equation*}
$$

where $\varepsilon_{0}$ is the far-field strain. Using Eq. (B.7), other constants could be found as demonstrated below

$$
\begin{equation*}
B_{8}=\varepsilon_{0} \tag{3.3}
\end{equation*}
$$

Using $u^{m(0)}(a, y)=u^{p(0)}(a, y)$, the $B_{1}$ coefficient can be obtained as follows

$$
\begin{equation*}
B_{1}=\left(B_{6}-B_{2}\right) a \tag{3.4}
\end{equation*}
$$

Equation (B.8) and the equation of the equilibrium, i.e. Eq. (3.5) ${ }_{1}$, lead to obtaining $B_{2}$ and $B_{6}$ as in Eqs. $(3.5)_{2,3}$

$$
\begin{equation*}
\sigma_{0}=f \bar{\sigma}_{y y}^{p(0)}+(1-f) \bar{\sigma}_{y y}^{m(0)} \quad B_{2}=p_{21} \sigma_{0}+p_{22} \varepsilon_{0} \quad B_{6}=p_{61} \sigma_{0}+p_{62} \varepsilon_{0} \tag{3.5}
\end{equation*}
$$

Also, $p_{21}, p_{22}, p_{61}$ and $p_{62}$ were found in Matlab software. Due to being so lengthy, they were not cited in this paper.

Then, the stresses in the imaginary platelet region $\left(l \leqslant y \leqslant l^{\prime}\right)$ were calculated. Similarly, the far-field solution and all the corresponding expressions of the general solution for the stress and strain components of this region could be obtained directly from those of the platelet region by considering $E_{p}=E_{m}$ and $\nu_{p}=\nu_{m}$. Using the same derivation procedures as the ones in the platelet region, the integral constants in this region were obtained

$$
\begin{array}{ll}
\widetilde{B}_{1}=\widetilde{B}_{5}=0 & \widetilde{B}_{4}=\widetilde{B}_{8}=\widetilde{\varepsilon}_{0} \\
\widetilde{B}_{3}=\widetilde{B}_{7}=\left(\varepsilon_{0}-\widetilde{\varepsilon}_{0}\right) l & \widetilde{B}_{2}=\widetilde{B}_{6}=\frac{\left(1-\nu_{m}^{2}\right) \sigma_{0}-E_{m} \widetilde{\varepsilon}_{0}}{\nu_{m} E_{m}} \tag{3.6}
\end{array}
$$

To calculate the far-field strains $\varepsilon_{0}$ and $\widetilde{\varepsilon}_{0}$, the following two boundary conditions could be used

$$
\begin{equation*}
u^{m(0)}(b, y)=\widetilde{u}^{m(0)}(b, y) \quad \frac{l}{l^{\prime}}\left[f E_{p}+(1-f) E_{m}\right] \varepsilon_{0}+\left(1-\frac{l}{l^{\prime}}\right) E_{m} \widetilde{\varepsilon}_{0}=\sigma_{0} \tag{3.7}
\end{equation*}
$$

Here, Matlab software was used to find $\varepsilon_{0}$ and $\widetilde{\varepsilon}_{0}$ strains. Because of being lengthy, they were not cited in this paper. Equation $(3.7)_{2}$ can be obtained from the boundary conditions and some simplifications which lead to having $l$ and $l^{\prime}$ inside the strain equations, equilibrium equations

$$
\begin{array}{ll}
\frac{l}{l^{\prime}} \sigma_{0}+\left(1-\frac{l}{l^{\prime}}\right) \sigma_{0}=\sigma_{0} & \sigma_{0}=f \sigma_{y y}^{p(0)}+(1-f) \sigma_{y y}^{m(0)} \\
\sigma_{0}=f \widetilde{\sigma}_{y y}^{p(0)}+(1-f) \widetilde{\sigma}_{y y}^{m(0)} & \sigma_{y y}^{m(0)}=E_{m} \varepsilon_{0}  \tag{3.8}\\
\sigma_{y y}^{p(0)}=E_{p} \varepsilon_{0} & \widetilde{\sigma}_{y y}^{m(0)}=\widetilde{\sigma}_{y y}^{p(0)}=E_{m} \widetilde{\varepsilon}_{0}
\end{array}
$$

Finally, by substituting $\varepsilon_{0}$ and $\widetilde{\varepsilon}_{0}$ and the above-obtained constants in the stress equations, the expressions for the far-field solutions in the two mentioned regions can be found as a function of $\sigma_{0}$.

### 3.2. Transient solution

In this part, the transient solution in the platelet region $(0 \leqslant y \leqslant l)$ will be first determined. The surface boundary conditions for the transient solution can be presented by

$$
\begin{equation*}
w^{m(T)}(x, 0)=0 \quad u^{m(T)}(b, y)=0 \tag{3.9}
\end{equation*}
$$

It is implied by these conditions that the transient solution did not alter the shape of the unit cell. Substituting the above conditions in the stress, the strain and displacement expressions resulted in

$$
\begin{equation*}
A_{3}=0 \quad A_{2}=-A_{1} \tan n b \tag{3.10}
\end{equation*}
$$

To determine two other coefficients, the following boundary conditions were used

$$
\begin{equation*}
u^{p(T)}(0, y)=0 \quad \sigma_{x x}^{m(T)}(a, y)=\sigma_{x x}^{p(T)}(a, y) \tag{3.11}
\end{equation*}
$$

Then, $A_{5}$ and $A_{6}$ were derived

$$
\begin{equation*}
A_{6}=0 \quad A_{5}=\frac{E_{m}}{E_{p}} \frac{1+\nu_{p}}{1+\nu_{m}}\left(A_{1}-A_{2} \tan n a\right) \tag{3.12}
\end{equation*}
$$

To find the unknown $n$, axial force equilibrium Eq. (3.13) was used. Matlab software was used for finding the optimum $n$

$$
\begin{equation*}
f \bar{\sigma}_{y y}^{p(T)}+(1-f) \bar{\sigma}_{y y}^{m(T)}=0 \tag{3.13}
\end{equation*}
$$

Afterwards, the transient solution was specified in the platelet end region $(l \leqslant y \leqslant l)$. The transient solution and all the corresponding expressions for the general solution of the stress and strain components in this region could be directly obtained from those of the platelet region by considering $E_{p}=E_{m}$ and $\nu_{p}=\nu_{m}$. Using the same derivation procedure and corresponding boundary conditions as the ones in the platelet region, the corresponding constants were achieved as follows

$$
\begin{equation*}
\widetilde{\tau}_{x y}^{m(T)}(b, y)=0 \quad \widetilde{w}^{m(T)}(a, y)=\widetilde{w}^{p(T)}(a, y) \quad \widetilde{\sigma}_{x x}^{m(T)}(a, y)=\widetilde{\sigma}_{x x}^{p(T)}(a, y) \tag{3.14}
\end{equation*}
$$

Also, the following constants were obtained

$$
\begin{equation*}
\widetilde{A}_{6}=0 \quad \widetilde{A}_{5}=\widetilde{A}_{1}-\widetilde{A}_{2} \tan \widetilde{n} a \quad \widetilde{A}_{2}=-\widetilde{A}_{1} \tan \widetilde{n} b \tag{3.15}
\end{equation*}
$$

To find the unknown $\widetilde{n}$, equilibrium Eq. (3.16) was used, similar to the real platelet field

$$
\begin{equation*}
f \overline{\tilde{\sigma}}_{y y}^{p(T)}+(1-f) \overline{\widetilde{\sigma}}_{y y}^{m(T)}=0 \tag{3.16}
\end{equation*}
$$

Using the following surface condition, Eq. $(3.17)_{1}, \widetilde{A}_{3}$ coefficient was also derived

$$
\begin{equation*}
\widetilde{\tau}_{x y}^{m}\left(x, l^{\prime}\right)=\widetilde{\tau}_{x y}^{p}\left(x, l^{\prime}\right)=0 \quad \widetilde{A}_{3}=-\widetilde{A}_{4} \frac{\sinh \widetilde{n} l^{\prime}}{\cosh \widetilde{n} l^{\prime}} \tag{3.17}
\end{equation*}
$$

Finally, $A_{4}$ and $\widetilde{A}_{4}$ coefficients were found using the following boundary conditions

$$
\begin{equation*}
\bar{\sigma}_{y y}^{p}(x, l)=\widetilde{\sigma}_{y y}^{p}(x, l) \quad \tau_{x y}^{m}(a, y)=\widetilde{\tau}_{x y}^{m}(a, y) \tag{3.18}
\end{equation*}
$$

## 4. Analytical and numerical predictions

To monitor the validity of the current analytical model, a comparison was made with the FEM calculations by ANSYS software. The schematic FEM model is also demonstrated in Fig. 1. The numerical calculations were performed on one quarter of the unit cell due to the existing symmetric boundary conditions. Eight nodded PLANE82 solid elements were applied for the purpose of meshing. Loading in ANSYS was via pressure applied to the element boundary line. All the simulations were performed under the plane stress condition. The boundary conditions required fixing both the $x$-displacement at $x=0$ and the $y$-displacement at $y=0$. The loading was applied to $y=l^{\prime}$. Only typical results were presented for $b / a=1.75, l / a=5$ and $l / l^{\prime}=0.5$ (platelet volume fraction was almost 0.285 ) in order to decrease the number of figures. The material properties were selected as $E_{m}=63 \mathrm{GPa}, E_{p}=402 \mathrm{GPa}, \nu_{m}=0.22$ and $\nu_{p}=0.23$ (Cannilloa et al., 2003). The applied stress was taken as $\sigma_{0}=200 \mathrm{MPa}$.


Fig. 2. Comparison and validation of the present model with Hsueh's model and numerical results

Figure 2 demonstrates the comparison and validation of the present model with the Hsueh model and its numerical results. Compared with Hsueh's results, the current model and FEM values of the stress components for the case of perfect bond were found to be in a good agreement.

To demonstrate the capabilities of the present model, displacements, strains, stresses in the matrix and platelet were given in the $x$ - and $y$-directions. It is worth considering that only typical results were presented in order to reduce the number of figures. The analytical and numerical curves of the normalized matrix in displacements in the $x$ - and $y$-directions on the outer surface of the unit cell and the platelet/matrix interface versus the normalized axial position are demonstrated in Fig. 3. As can be observed, considerable agreements were obtained between the analytical and numerical predictions. Figure 4 depicts the analytical and numerical curves of the shear stress and $x$-direction stresses on the outer surface of the unit cell $(x=b)$ and the platelet-matrix interface versus the normalized axial position $y / a$.


Fig. 3. Analytical and numerical curves of the matrix displacements vs. the normalized axial position


Fig. 4. Analytical and numerical curves of the matrix stress vs. the normalized axial position

The given comparisons confirmed considerable strong prediction ability of the analytical solution for the elastic field distribution in such a complicated system. There are some small inconsistencies in singular behavior on the platelet end plane between the analytical and numerical solutions, which can be probably attributed to the limited prediction ability of the finite element numerical method for the stress singularity. These calculations also demonstrated that the same consistent predictions could be achieved for all the strain components and over a great range of material properties and geometries, which were not included here.

## 5. Conclusions

An analytical model was developed for the analysis of the 3D elastic stress field in a platelet reinforced composite subjected to an axial load. The present stress field solution involved two regions, i.e. the matrix region surrounding the platelet and the platelet region. The derived analytical expressions for the matrix and platelet stress fields precisely satisfied both equilibrium and compatibility conditions of the theory of elasticity. Furthermore, since the interface continuity conditions and axial force equilibrium conditions were taken into account, the overall equilibrium was ensured rigorously within the platelet, matrix and between the platelet and the matrix.

Apart from the investigations based on the shear-lag theory, the stress transfer from the matrix to the platelet was obtained through the interface continuity conditions and the axial force equilibrium conditions. Furthermore, this model of the platelet reinforced composite presented all stress, strain and displacement components in the matrix and platelet; in contrast, shear-lag model only could predict the $y$-direction average stress in the platelet and the interface shear stress.

Because the number of boundary conditions, equilibrium and compatibility conditions was more than the number of unknown coefficients $\left(A_{j}, B_{j}, n, \widetilde{n}\right)$, optimization methods were used for finding the best answers.

## A. Solution for matrix displacements

$$
\begin{equation*}
\frac{\partial^{2} u}{\partial x^{2}}+\frac{\partial^{2} u}{\partial y^{2}}=0 \tag{A.1}
\end{equation*}
$$

Using the method of separation of variables for writting $u(x, y)$ as

$$
\begin{equation*}
u(x, y)=Y(y) X(x) \tag{A.2}
\end{equation*}
$$

substitution of $u(x, y)$ into Eq. (A.1) leads to

$$
\begin{equation*}
\frac{\partial^{2} X}{\partial x^{2}}+n X=0 \quad \frac{\partial^{2} Y}{\partial x^{2}}-n Y=0 \tag{A.3}
\end{equation*}
$$

Then, the following can be given

$$
\begin{equation*}
X=A_{1} \sin n x+A_{2} \cos n x \quad Y=A_{3} \sinh n y+A_{4} \cosh n y \tag{A.4}
\end{equation*}
$$

So

$$
\begin{equation*}
u^{m(T)}(x, y)=\left(A_{1} \sin n x+A_{2} \cos n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \tag{A.5}
\end{equation*}
$$

For the far-field case $n=0$, then

$$
\begin{equation*}
X^{m(0)}=B_{1}+B_{2} x \quad Y^{m(0)}=C_{1}+C_{2} y \tag{A.6}
\end{equation*}
$$

So

$$
\begin{equation*}
u^{m(0)}(x, y)=\left(B_{1}+B_{2} x\right)\left(C_{1}+C_{2} y\right) \tag{A.7}
\end{equation*}
$$

where $B_{1}, B_{2}, C_{1}$ and $C_{2}$ are constants. The boundary conditions can be used with some simplifications, which results in

$$
\begin{equation*}
u^{m(0)}(x, y)=B_{1}+B_{2} x \tag{A.8}
\end{equation*}
$$

Substitution of elements of Eqs. (A.5), (A.8) into Eq. (2.1) leads to

$$
\begin{align*}
& w^{m(T)}(x, y)=\left(-A_{1} \cos n x+A_{2} \sin n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right) \\
& w^{m(0)}(x, y)=B_{3}+B_{4} y \tag{A.9}
\end{align*}
$$

## B. Boundary conditions

$$
\begin{array}{ll}
u^{m}(b, y)=\widetilde{u}^{m}(b, y) & \tau_{x y}^{m}(b, y)=\widetilde{\tau}_{x y}^{m}(b, y)=0 \\
w^{m}(x, 0)=w^{p}(x, 0)=0 & \tau_{x y}^{m}(x, 0)=\tau_{x y}^{p}(x, 0)=0 \\
\widetilde{w}^{m}\left(x, l^{\prime}\right)=\widetilde{w}^{p}\left(x, l^{\prime}\right) & \widetilde{\tau}_{x y}^{m}\left(x, l^{\prime}\right)=\widetilde{\tau}_{x y}^{p}\left(x, l^{\prime}\right)=0 \tag{B.1}
\end{array}
$$

The interface continuity conditions on the platelet-matrix interface $(x=a)$

$$
\begin{array}{ll}
\varepsilon^{m}(a, y)=\varepsilon^{p}(a, y) & \sigma_{x x}^{m}(a, y)=\sigma_{x x}^{p}(a, y) \\
\widetilde{\varepsilon}^{m}(a, y)=\widetilde{\varepsilon}^{p}(a, y) & \tilde{\sigma}_{x x}^{m}(a, y)=\widetilde{\sigma}_{x x}^{p}(a, y) \tag{B.2}
\end{array}
$$

The continuity conditions on the platelet end surface $(x=l)$

$$
\begin{array}{ll}
\bar{\sigma}_{y y}^{m}(x, l)=\overline{\widetilde{\sigma}}_{y y}^{m}(x, l) & \bar{\sigma}_{y y}^{p}(x, l)=\bar{\sigma}_{y y}^{p}(x, l) \\
\tau_{y y}^{m}(x, l)=\widetilde{\tau}_{y y}^{m}(x, l) & w^{m}(x, l)=\widetilde{w}^{m}(x, l) \tag{B.3}
\end{array}
$$

## C. General solutions for the stress and strain components

According to the theory of elasticity, the elastic constituent relations could be written as follows

$$
\begin{align*}
\tau_{x y} & =\tau_{y x}=\frac{E}{2(1-\nu)} \gamma_{x y} & \sigma_{x x} & =\frac{E}{1-\nu^{2}}\left(\varepsilon_{x x}+\nu \varepsilon_{y y}\right) \\
\sigma_{y y} & =\frac{E}{1-\nu^{2}}\left(\nu \varepsilon_{x x}+\varepsilon_{y y}\right) & \varepsilon_{x x} & =\frac{\partial u}{\partial x}  \tag{C.1}\\
\varepsilon_{y y} & =\frac{\partial w}{\partial y} & \gamma_{x y} & =\gamma_{y x}=\frac{\partial u}{\partial y}+\frac{\partial w}{\partial x}
\end{align*}
$$

where $\sigma, \varepsilon, \tau$ and $\gamma$ are the normal stress and strain and the shear stress and strain, respectively. The following equations present the far-field solution of the matrix. Note that, for the end fiber region; i.e. $l \leqslant y \leqslant l^{\prime}$, all the coefficients should have the tilde

$$
\begin{align*}
\sigma_{x x}^{m(0)}(x, y) & =\frac{E_{m}}{1-\nu_{m}^{2}}\left(B_{2}+\nu_{m} B_{4}\right) & \sigma_{y y}^{m(0)}(x, y)=\frac{E_{m}}{1-\nu_{m}^{2}}\left(\nu_{m} B_{2}+B_{4}\right) \\
\tau_{x y}^{m(0)}(x, y) & =0 & \varepsilon_{x x}^{m(0)}(x, y)=B_{2}  \tag{C.2}\\
\varepsilon_{y y}^{m(0)}(x, y) & =B_{4} & \gamma_{x y}^{m(0)}(x, y)=\gamma_{y x}^{m(0)}=0
\end{align*}
$$

The far-field solution for the fiber and imaginary fiber regions will be shown as follows. It is worth considering that, for the imaginary fiber, $E_{p}$ and $\nu_{p}$ should be converted to $E_{m}$ and $\nu_{m}$, and all the coefficients should have the tilde

$$
\begin{array}{ll}
\sigma_{x x}^{p(0)}(x, y)=\frac{E_{p}}{1-\nu_{p}^{2}}\left(B_{6}+\nu_{p} B_{8}\right) & \sigma_{y}^{p(0)}(x, y)=\frac{E_{p}}{1-\nu_{p}^{2}}\left(B_{8}+\nu_{p} B_{6}\right) \\
\tau_{x y}^{p(0)}(x, y)=0 & \varepsilon_{x x}^{p(0)}(x, y)=B_{6}  \tag{C.3}\\
\varepsilon_{y y}^{p(0)}(x, y)=B_{8} & \gamma_{x y}^{p(0)}(x, y)=\gamma_{y x}^{p(0)}(x, y)=0
\end{array}
$$

The transient solution of the matrix is given below. For the end platelet region; i.e. $l \leqslant y \leqslant l^{\prime}$, all the coefficients should have the tilde

$$
\begin{align*}
\sigma_{x x}^{m(T)}(x, y) & =\frac{n E_{m}}{1+\nu_{m}}\left(A_{1} \cos n x-A_{2} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\sigma_{y y}^{m(T)}(x, y) & =\frac{n E_{m}}{1+\nu_{m}}\left(-A_{1} \cos n x+A_{2} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\tau_{x y}^{m(T)}(x, y) & =\frac{n E_{m}}{1+\nu_{m}}\left(A_{1} \sin n x+A_{2} \cos n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right)  \tag{C.4}\\
\varepsilon_{x x}^{m(T)}(x, y) & =n\left(A_{1} \cos n x-A_{2} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\varepsilon_{y y}^{m(T)}(x, y) & =n\left(-A_{1} \cos n x+A_{2} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\gamma_{x y}^{m(T)}(x, y) & =2 n\left(A_{1} \sin n x+A_{2} \cos n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right)
\end{align*}
$$

For the transient solution of the platelet and imaginary platelet, one may reach the following equations. For the imaginary platelet, the $E_{p}$ and $\nu_{p}$ should be converted to $E_{m}$ and $\nu_{m}$, and all the coefficients should have the tilde

$$
\begin{align*}
\sigma_{x x}^{p(T)}(x, y) & =\frac{n E_{p}}{1+\nu_{p}}\left(A_{5} \cos n x-A_{6} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\sigma_{y y}^{p(T)}(x, y) & =\frac{n E_{p}}{1+\nu_{p}}\left(-A_{5} \cos n x+A_{6} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\tau_{x y}^{p(T)}(x, y) & =\frac{n E_{p}}{1+\nu_{p}}\left(A_{5} \sin n x+A_{6} \cos n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right)  \tag{C.5}\\
\varepsilon_{x x}^{p(T)}(x, y) & =n\left(A_{5} \cos n x-A_{6} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\varepsilon_{y y}^{p(T)}(x, y) & =n\left(-A_{5} \cos n x+A_{6} \sin n x\right)\left(A_{3} \sinh n y+A_{4} \cosh n y\right) \\
\gamma_{x y}^{p(T)}(x, y) & =2 n\left(A_{5} \sin n x+A_{6} \cos n x\right)\left(A_{3} \cosh n y+A_{4} \sinh n y\right)
\end{align*}
$$

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